TCP and BBR

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APNIC
Computer Networking is all about moving data

- The way in which data movement is controlled is a key characteristic of the network architecture
- The Internet protocol passed all controls to the end systems, and treated the network as a passive switching environment
- But that was many years ago, and since then we have seen the deployment of active middleware in networks and control traffic flows
- All this is changing again as we see a what could well be a new generation of flow control algorithms being adopted in the Internet
- Lets look at one of the more interesting initiatives: Bottleneck Bandwidth and Round-Trip Time (BBR)
Let's talk about speed

• How fast can we push a single session to move data through the network?

• Session speed is the result of a combination of:
  • available transmission speeds,
  • end-to-end latency and
  • protocol efficiency
  – All of these factors are critical
The Evolution of Speed

1980’s
  – TCP rates of Kilobits per second

1990’s
  – TCP rates of Megabits per second

2000’s
  – TCP rates of Gigabits per second

2010’s
  – TCP rates of Gigabits per second
Today

- Optical transmission speeds are approaching Terrabit capacity
- But peak TCP session speeds are not keeping up
- What’s going on?
TCP

- The Transmission Control Protocol is an end-to-end protocol that creates a reliable stream protocol from the underlying IP datagram device
- TCP operates as an adaptive rate control protocol that attempts to operate fairly and efficiently
TCP Design Objectives

To maintain an average flow which is **Efficient** and **Fair**

- **Efficient:**
  - Minimise packet loss
  - Minimise packet re-ordering
  - Do not leave unused path bandwidth on the table!

- **Fair:**
  - Do not crowd out other TCP sessions
  - Over time, take an average $1/N$ of the path capacity when there are $N$ other TCP sessions sharing the same path
It's a Flow Control process

- Think of this as a multi-flow fluid dynamics problem
- Each flow has to gently exert pressure on the other flows to signal them to provide a fair share of the network, and be responsive to the pressure from all other flows
TCP Control

TCP is an **ACK Pacing** protocol

Data sending rate is matched to the ACK arrival rate
TCP Control

ACK pacing protocols relate to a past network state, not necessarily the current network state

- The ACK signal shows the rate of data that left the network at the receiver that occurred at ½ RTT back in time

- So if there is data loss, the ACK signal of that loss is already ½ RTT old!
  - So TCP should react quickly to ‘bad’ news
- If there is no data loss, that is also old news
  - So TCP should react conservatively to ‘good’ news
"Classic TCP" - TCP Reno

• Additive Increase Multipliciative Decrease (AIMD)
  – While there is no packet loss, increase the sending rate by One Segment (MSS) each RTT interval
  – If there is packet loss decrease the sending rate by 50% over the next RTT Interval

• Start Up
  – Each RTT interval, double the sending rate
  – We call this “slow start” – probably because its anything but slow!!!
Idealised TCP Reno

- **Slow Start**: Rate doubles each RTT interval.
- **Congestion Avoidance**: Rate increases by 1 MSS per RTT.
- **Notification of Packet Loss**: Via Duplicate ACKs, RENO halves its sending rate on Packet Loss.
TCP RENO and Idealized Queue Behaviour

Total Queue Capacity (Onset of Packet Loss)

Link Capacity Capacity (Onset of Queuing)

Network Buffers Fill

Network Buffers Drain
Reno is too slow

- TCP Reno tries to oscillate between sending rates $R$ and $2 \times R$ that span the actual link capacity.

- It increases its sending rate slowly so it’s really lousy when trying to run at very high speed over long delay networks.

- It over-corrects on loss and leaves available path capacity idle.
  - 10Gbps rates over 100ms RTT demands a packet loss rate of less than 0.000003%.
  - An average 1% loss rate over a 100ms RTT can’t operate faster than 3Mbps.
Faster than Reno?

- Can we make TCP faster and more efficient by changing the way in which the sending rate is inflated?
- Of course!
Refinements to RENO

• There have been many efforts to alter RENO’s flow control algorithm.

• In a loss-based AIMD control system the essential parameters are the manner of rate increase and the manner of loss-based decrease.
  – For example:
    MulTCP behaves as if it were N simultaneous TCP sessions: i.e. increase by N segments each RTT and rate drop by 1/N upon packet loss.

• What about varying the manner of rate increase away from AI?
Enter CUBIC

- CUBIC is designed to be useful for high speed sessions while still being ‘fair’ to other sessions and also efficient even at lower speeds

- Rather than probe in a linear manner for the sending rate that triggers packet loss, CUBIC uses a non-linear (cubic) search algorithm
CUBIC and Queue formation

- Total Queue Capacity (Onset of Packet Loss)
- Link Capacity Capacity (Onset of Queuing)

Network Buffers Fill
Network Buffers Drain
CUBIC assessment

• Can react quickly to available capacity in the network
• Tends to sit for extended periods in the phase of queue formation
• Can react efficiently to long fat pipes and rapidly scale up the sending rate
• Operates in a manner that tends to exacerbate ‘buffer bloat’ conditions
Can we do better?

• Lets look at the model of the network once more, and observe that there are three ‘states’ of flow management in this network:
  – Under-Utilised – where the flow rate is below the link capacity and no queues form
  – Over-Utilised – where the flow rate is greater that the link capacity and queues form
  – Saturated – where the queue is filled and packet loss occurs

• Loss-based control systems probe upward to the Saturated point, and back off quickly to what they guess is the Under-Utilised state in order to the let the queues drain

• But the optimal operational point for any flow is at the point of state change from Under to Over-utilised, not at the Saturated point
RTT and Delivery Rate with Queuing

Round Trip Time

- $\text{RTT}_{\text{base}}$
- Slope $= \frac{1}{\text{Bw}}$
- Packet Loss

Data Volume In-Flight

Delivery Rate

- Slope $= \frac{1}{\text{RTT}_{\text{base}}}$
- Bw
- Optimum Operating Point
- Loss-Based Congestion Control Point

Under-Utilised | Over-Utilised | Saturated
How to detect the onset of queuing?

• By carefully measuring the Round Trip Time!
BBR Design Principles

• Probe the path capacity only intermittently

• Probe the path capacity by increasing the sending rate for a short interval and then drop the rate to drain the queue:
  – If the RTT of the probe equals the RTT of the previous state then there is available path bandwidth that could be utilised
  – If the RTT of the probe rises then the path is likely to be at the onset of queuing and no further path bandwidth is available

• Do not alter the path bandwidth estimate in response to packet loss

• Pace the sending packets to avoid the need for network buffer rate adaptation
Idealised BBR profile

sending rate

network queues
BBR Politeness?

- BBR will probably not constantly pull back when simultaneous loss-based protocols exert pressure on the path’s queues.
- BBR tries to make minimal demands on the queue size, and does not rely on a large dynamic range of queue occupancy during a flow.
From Theory to Practice

• Lets use BBR in the wild

• I’m using iperf3 on Linux platforms (Linode)
  – The platforms are dedicated to these tests

• It’s the Internet
  – The networks paths vary between tests
  – The cross traffic is highly variable
  – No measurement is repeatable to a fine level of detail
Cubic vs BBR over a 12ms RTT 10G circuit
Wow!

• That was BRUTAL!

• As soon as BBR started up it collided with CUBIC, and BBR startup placed pressure on CUBIC such that CUBIC’s congestion window was reduced close to zero

• At this stage CUBIC’s efforts to restart its congestion window appear to collide with BBR’s congestion control model, so CUBIC remains suppressed
  – The inference is that BBR appears to be operating in steady state with an ability to crowd out CUBIC
BBR vs Cubic – second attempt

Same two endpoints, same network path across the public Internet

Using a long delay path AU to Germany via the US
**BBR vs Cubic**

The Internet is capable of offering a 400Mbps capacity path on demand!

In this case BBR is apparently operating with filled queues, and this crowds out Cubic.

BBR does not compete well with itself, and the two sessions oscillate in getting the majority share of available path capacity.
BBR and Loss Recovery

Packet loss causes retransmission that appears to occur in addition to the stable link capacity model used by BBR.

Once loss is reduced, BBR maintains a more consistent sending model.
We used 50 parallel BBR streams between the same two endpoints (200ms RTT)

In this larger setup the majority of sessions managed to equilibrate between each other and evenly share the path bandwidth.
So what can we say about BBR?

It’s “interesting” in so many ways:

- It’s a move away from the more common loss-based flow control protocols
- It looks like it will operate very efficiently in a high-speed small-buffer world
  - High speed small buffer chips are way cheaper, but loss-based TCP reacts really badly to small buffers by capping its flow rate
- It will operate efficiently over ECMP paths, as it is relatively impervious to packet re-ordering
- It also looks as if it will operate efficiently in rate policed environments
- Unlike AIMD systems, it will scale from Kbps to Gbps over long delay paths very efficiently
- It resists the conventional network-based traffic control mechanisms
Why use BBR?

• Because it achieves
• Its incredibly efficient
• It makes minimal demands on network buffer capacity
• It’s fast!
Why **not** use BBR?

- Because it **over achieves**!
- The classic question for many Internet technologies is scaling
  - “what if everyone does it?”
  - BBR is not a scalable approach
  - It works so well while it is used by just a few users, some of the time
  - But when it is active, BBR has the ability to slaughter concurrent loss-based flows
  - Which sends all the wrong signals to the TCP ecosystem
    - The loss-based flows convert to BBR to compete on equal terms
    - The network is then a BBR vs BBR environment, which is unstable
Is this BBR experiment a failure?

Is it just too ‘greedy’ and too ‘insensitive’ to other flows to be allowed out on the Internet to play?

- Many networks have been provisioned as a response to the aggregate behaviours of loss-based TCP congestion control
- BBR changes all those assumptions, and could potentially push many networks into sustained instability
- We cannot use the conventional network control mechanisms to regulate BBR flows
  - Selective packet drop just won’t create back pressure on the flow
Where now?

BBR 2.0

- Alter BBR’s ‘sensitivity’ to loss rates, so that it does not persist with an internal bandwidth delay product (BDP) that exceeds the uncongested BDP. This measure would moderate BBR 1.0’s ability to operate for extended periods with very high loss levels.
- Improve the dynamic sharing fairness by moderating the Bandwidth Delay Product by using an estimated ‘fair’ proportion of the path BDP.
- Accommodate the signal distortion caused by ACK stretching middleware.
- Place an upper bound on the volume of in-flight data.
- Alter the +/- 25% probe factors dynamically (i.e. allow this to be less than 25% overload).
The new Network Architecture

• We are seeing a shift away from network-level active middleware back towards edge-centric control in the Internet

• QUIC and BBR are instances of a recent push back from the network-level QoS bandwidth control mechanisms, and result in greater levels of autonomous control being passed back to the end hosts
What is all this telling us?

• The Internet still contains a large set of important unsolved problems

• Moving large data sets over high speed networks requires a different approach to what we are doing today

• BBR seems to be a step in an interesting direction, particularly for very high speed networking

• But it still calls for more research and more testing at scale
That's it!

Questions?